

Instruction Manual

MICRO CONTROLLER E Z SERIES

TYPE: PYZ 4

5

7

9

INTRODUCTION

You are now the owner of Fuji's Digital Temperature Controller. Before using, be sure to check the instrument for correct specifications. This instruction manual has been prepared for final users.

The product conforms to the requirements of the Electromagnetic compatibility Directive 89/336/EEC as detailed within the technical construction file number TN510404. The applicable standards used to demonstrate compliance are:

EN 50081-1: 1992 Conducted and Radiated emissions
EN 50082-1: 1992 Radiated immunity, ESD and FBT
(The unit meets Class A limits for conducted Emissions.)

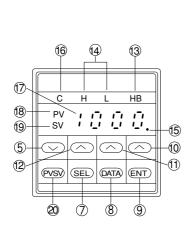
The unit also complies with the part of Immunity standards.

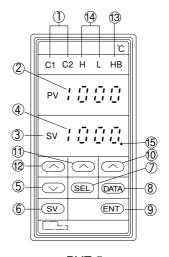
IEC 1000-4-2: 1995 level 3, IEC 1000-4-3: 1995 level 3 IEC 1000-4-4: 1995 level 3, IEC 1000-4-8: 1993 level 4

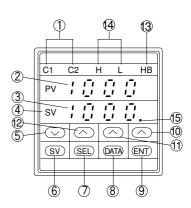
CONTENTS

		Page
Intr	oduction	i
1.	Functions of their keys and displays	1
2.	Operation	
	2.1 Preparation for operation	2
3.	Fault indication	6
4.	Use of dual output type (option)	7
5.	Use of heater break alarm (option)	8
6.	Change of functions	10
	6.1 Kinds of second parameter and meanings	10
	6.2 Function setting	11
7.	Outline dimensions and panel cutout	16
8.	Terminal connection diagram	17
9.	Control/alarm output and indicating lamp	19
10.	Cautions for installation and wiring	20
11.	Specifications	23
12.	Ordering code	24

1. FUNCTIONS OF THEIR KEYS AND DISPLAYS







PYZ 4

PYZ 5

PYZ 7, 9

Fig. 1

Table 1

Item	Function
① Control output lamp (green)	C1: Control output "1" indication (lamp is lit at ON) C2: Control output "2" indication(lamp is lit at ON) (option)
② Measured value (PV) lamp (red)	Indication of measured value
③ Set value (SV) lamp (green)	Lamp is lit whle indicating set value (SV).
④ Parameter lamp (green)	Indication of set value (SV) and various parameters (PID, high/low alarm, heater break alarm, etc.)
(5) Down-key (common to all digits)	Numeric value of digit selected by up-key goes down. When parameters do not flicker, press the key. Parameters are indicated sequentially. SEL key indication and Down-key indication are reverse.
Direct SV select key	Set value (SV) is indicated by pressing this key.
7 Parameter select key	Parameters are indicated in order at each press of this key.
8 Data key	Indication of parameter data selected by parameter select key.
Data entry key	Data are registered after they have been changed. (Changed data cannot be registered unless this key is pressed.)
① 1-digit up-key	Numerical value of digit flickers at a press. It goes up while repeating to press this key.
① 10-digit up-key	Numeric value of 10-digit flickers at a press. It goes up while repeating to press this key.
② 100-digit up-key	Numeric value of 100-digit flickers at a press. It goes up while repeating to press this key. It returns to "0" after it reaches "9" and, at the same time, the 1000th digit goes up by "1".
(I3) Heater break alarm lamp (red)	Lamp is lit at ON of heater break alarm output (option)
(4) Alarm lamp (red)	H: Lamp is ON at high alarm (option) L: Lamp is ON at low alarm (option)
(5) Auto tuning lamp	Lamp flickers during PID auto tuning.
(f) Control output lamp (green)	Lamp is lit at ON of control output.
17 Parameter indication	Indication of measured value (PV), set value (SV) and various parameters.
Measured value (PV) lamp (red)	Lamp is lit at indication of measured value (PV)
Set value (SV) lamp (red)	Lamp is lit at indication of set value (SV)
20 PV/SV select key	Selection of measured value (PV) or set value (SV) at each press of this ke

PYZ4

2. OPERATION

	-	the power, the measured value (PV) and set value (SV) indicators show
2.1	Prep	paration for operation
	before parame For ch The co	sure correct operation of the controller, it is necessary to set parameters fitted to the controlled system operating, according to the procedures shown in (2) setting method of parameters. While setting eters, be sure to turn OFF the operation of the operation terminal side for the sake of safety. Langing the ordered specifications after purchase, refer to "6. CHANGE OF FUNCTIONS". Controller (PYZ) unit requires about 2 hours for thermal stability. The to start measurements after 2 hours or more since the power has been turned ON.
(1	Table that s Press the (s of parameters and meaning e 2.1 List of first block parameters shows kinds of parameters of the controller and meaning. Note some parameters are not indicated depending on the code symbols specified by you. Sing the SEL key, parameters are indicated in the order of SV \rightarrow P \rightarrow Ivv. \rightarrow LoC \rightarrow SV. Pressing \rightarrow key, parameters are indicated in the order of SV \rightarrow LoC \rightarrow SV. (When the data of meters are indicated, the parameters can not be changed by these operations.) To return indicating SV another parameter indicated, press the SV key.
(2	Refer When	ng method of parameters r to the Table 2-2, 2-3 (page 5) to set each value of parameters. n the PID value has not been determined at the operation with PID action, the auto tuning function ld be used.
(3	This the fu	nd block parameters controller is provided with the second block parameter to determine the controllers functions besides unctions shown in "List of the first block parameter". Refer to "List of the second block parameter" e 10).
(4		is left for 30 seconds after key operation, the parameter indication is reset to SV indication natically. (In case of PYZ4, the parameter is turned to PV indication.)
(5) Minu	is value setting
	value When	n altering plus sign to minus, press the \bigvee key after setting all digits to "0". Then, minus numeral es shall be indicated. Set the value to the required value by operating the \bigwedge key or the \bigvee key. In altering minus sign to plus, press the \bigwedge key after setting all digits to "0". Then, the minus code shall disappear. Set the value to the required value by operating the \bigwedge key or the \bigvee key.
(6	The I funct	tuning (AT) operation PID parameters can be automatically measured, calculated and set by the controller using auto-tuning tion. auto-tuning should be performed when P.I.D value has not been set before operating P.I.D mode.
		The auto-tuning function should be used after the set value (SV), alarm setting (AL, AH) and proportional cycle (TC) [Reference: SSR/SCC drive output; 2 sec, contact output; 30 sec.] are set up.
		Meaning of auto-tuning data 0: Auto-tuning is disable 1: Standard type auto-tuning PV is compared with Sv during auto-tuning. 2: Low PV type PV is compared with (SV 10% (SS) during outs tuning.
		PV is compared with (SV-10%FS) during auto-tuning.

- (c) Auto-tuning startup operation
 - O Press the parameter select key (SEL) to indicate 27 Ξ 7
 - O Press the Data key DATA to indicate auto-tuning data. Auto-tuning disable code "0" is indicated.
- Press the 1-digit up-key for setting the code of autotuning. (Standard type: 1 Low PV type: 2)
- O Press the 1-digit up-key (\(\lambda\) to set "1" when the standard type auto-tuning is required. The auto-tuning of the standard type is executed. (When the low-PV type autotuning, set "2".)



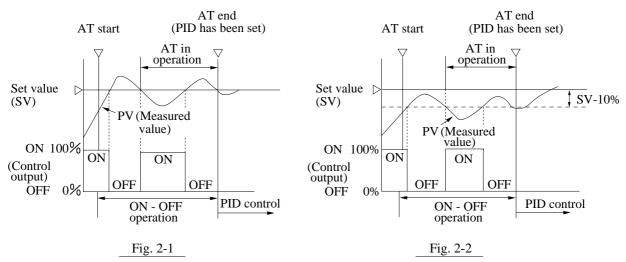
- Press the Data entry key ENT to start auto-tuning. The auto-tuning lamp flickers during auto-tuning.
- <u>._</u>, Auto-tuning lamp decimal point on ` the 1st digit

(AT).

Ū

- O Press the direct SV select key or PV/SV select key to indicate SV.
- At the end of auto-tuning, flashing goes off and the autotuning parameter At is automatically reset to "0" and changed automatically to the next parameter.
- (d) When the auto-tuning is completed, the PID parameter is saved even if the power is turned OFF. Auto-tuning is not required again for the following operation. However, the auto-tuning should be performed from the beginning when the power is turned OFF in the middle of auto-tuning.
- (e) During auto-tuning, it is under ON-OFF operation (2-position operation) and PV may be oscillated greatly depending on process. If it is not desirable, do not use the auto-tuning function.
- (f) Do not use auto-tuning for a quick response process such as pressure control, flow control, etc.
- (g) When auto-tuning is not completed within 4 hours, it means that the auto-tuning function is abnormal. In such a case, check the control system (input/output wiring) and also check to make sure that the control output operation conforms with the controlled object. Then, repeat the auto-tuning once
- (h) When SV has largely changed or the process operating condition has been changed, carry out the auto-tuning again.
- (i) During auto-tuning, PV and the output vary as shown in Figs. 2-1 and 2-2.
- (7) With the PYZ left for 30 seconds after key operation, the parameter indication is reset to SV indication automatically. (In case of PYZ4, the parameter is reset to PV indication.)

Standard type Low PV type



When AT lamp is lit, it is an indication of ON-OFF operation (2-position operation), and measured Note) value (PV) is fluctuated.

List of first block parameters

Table 2-1

Parameter symbol	Item	Meaning	Description	Initial value prior to delivery	Remarks
SV	sv	Set value	Settable within the input range	"0" or ordering specification	
P	P	Proportional band	Setting range: 0.0 to 999.9% (at input range)	3.0	2-position operation* at setting "0" (TC should also be set to "0")
Ć.	I	Integral time	Setting range: 0 to 9999 sec.	0	Integral operation is OFF at "0".
đ	D	Derivative time	Setting range: 0 to 3600 sec.	0	Derivative operation* is OFF at "0".
RI <u>.</u>	A L	Low	Settable within the input range. Lower limit value of the alarm is set.	10	Not indicated without alarm function.
ЯН	АН	High	Settable within the input range. Upper limit value of the alarm is set.	10	Not indicated without alarm function.
71 <u>7</u>	TC	Proportional cycle of control output 1	Proportional cycle of control output 1 is settable. Setting range: 1 to 150 sec.	Contact output :30 SSR drive output: 2	Not indicated at current output.
H95	HYS	Hysteresis width of 2-position operation	Setting range: 0.0 to 20.0%FS Hyeresis width at 2-position operation is settable.	0.3	
H5	Hb	Heater break alarm	Setting range: 0 to 50.0A. Operation value to detect heater break is settable. (Option)	0.0	The alarm function is OFF at "0.0". Not indicated without heater break alarm function.
នា	AT	Auto tuning	Used for setting PID parameters by auto- tuning function. 0: Disable or reset auto-tuning 1: Standard type auto-tuning at SV 2: Lower PV type auto-tuning at SV-10FS	0	Auto-tuning is started when "AT" hasbeen set to "1" or "2" and the "AT" is automatically reset to "0" at the end of Auto-tuning.
70.8	TC2	Proportional cycle of control output 2	Proportional cycle of control output 2 is settable. Setting range: 1 to 150 sec.	Contact output :30 SSR drive output: 2	Not indicated without function of control output 2 and at current output.
Cool	CooL	Proportional band coeffcient of cooling side	Cooling side proportional band factor is settable (setting range: 0, 0.1 to 99.9) ON-OFF operation at setting "0"	1.0	Not indicated without function of control output 2.
db	db	Proportional band shift of cooing side	Cooling side output value is shifted. Setting range: -50.0 to +50.0	0.0	Not indicated without function of control output 2
PLC I	PLC1		Setting need not be changed	Specified by manufacturer	
PHC I	PHC1		Same as above	Specified by manufacturer	
5 <i>8</i> 1.	BAL		Same as above	Specified by manufacturer	
8-	AR		Same as above	Specified by manufacturer	
LoC	LoC	Key lock	Selecting "able" or "disable" of changing of parameter set value. 0: All parameter set values are changeable 1: Inhibit changing the all parameter set values. 2: Inhibit changing the all parameter set values other than "SV"	0	

Caution: Each parameter should be used within the setting range shown in the instruction manual. If it is used beyond the setting range, it can result in unexpected trouble.

Setting of set value (SV)

Table 2-2

Contents of operation	Setting of SV to 250	
Key operation	Description	Indication
(SV) (PV/SV) for PYZ4	Press the SV key to indicate set value. (This operation can be omitted when a set value is indicated.)	svŏ 💿
	• Press key of any digit to be set. In this example, the key of 10-digit is pressed. The 10-digit indication flickers.	svö ø å ø
	• Press the key (5 times) to indicate "5".	svö o 5 o
	• Press key of 100-digit. The 100-digit indication flickers.	svő g 5 o
	• Press the \bigcirc key (2 times) to indicate "2".	svö 💢 5 o
ENT (m)	 Press the ENT key. The indication stops flickering and the set value 250°C is indicated. — Operation is completed. — 	svÖ 250

Setting of low alarm (AL)

Table 2-3

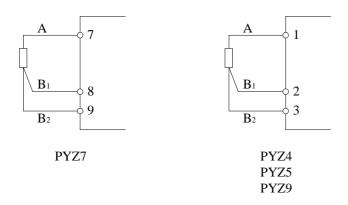
Contents of operation	Setting of low alarm (AL) from 0 to 100	
Key operation	Description	Indication
SEL	• Press the SEL key to indicate $[\vec{x}_{11}]$. $(\vec{x}_{12} \rightarrow \vec{x}_{12} \rightarrow \vec{x}_{11})$	81
(DATA)	• Press the DATA key to indicate data. Latest alarm set value is displayed. (In this exapmle, "0")	
	• Press key of any digit to be set. In this example, the indication of 100-digit flickers.	
	• Press the \bigcirc key (once) to indicate "1".	
ENT (m)	Press the ENT key. Indication stops flickering, and the alarm set value "100" is set and indicated. The indication is shifted automatically to the next parameter.	8 8

3. FAULT INDICATION

The controller has a fault indicating function so that the cause of fault can be removed quickly. After the cause has been removed, be sure to turn off and then turn on the power switch.

Table 3-1

Indication	Cause	Control output		
ייייייייי	Burnout of thermocouple sensor (upscale burnout) Burnout of resistance bulb sensor (upscale burnout)	① In case of upscale burnout (standard OFF or less than 4 mA in reverse action ON or more than 20 mA in normal action ② In case of downscale burnout		
	 Burnout of thermocouple sensor (downscale burnout) Burnout of resistance bulb sensor (downscale burnout) 	ON or more than 20 mA in reverse action OFF or less than 4 mA in normal action		
יניינייניי	① PV reading is more than "the range upscale value +30% FS" (Note)	Goes on control Note) Even when the PV value is over the range		
	 Short-circuit of resistance bulb sensor (between A and B) PV reading is less than "the range downscale value -30% FS" (Note) 	within +30% FS, it becomes sensor burnout display, and the control output is output, if the input voltage exceeds the burnout detecting point.		
HB Lamp ON	Heater burnout	Normal control		



4. USE OF DUAL OUTPUT TYPE (OPTION)

(1) Function description

The dual output type has 2 control outputs for one input signal and set value (SV). Control output 1 is used for heating, while control output 2 is used for cooling, respectively. Output signal is any combination with contact output, SSR drive output and 4 to 20mA DC output which are available according to the code symbols. The dual output type has the parameters TC2, cool, db in addition to those of the standard type. In dual type, the proportional band of control output 1 is P/2. The proportional band of control output 2 is described below. However, the max. value should be limited to P/2.

By setting the parameter cool to 0.0, cooling control is set to ON-OFF control. (Note that hysteresis is not attached.)

Example: In case of P = 20 (%) and cool = 0.5 proportional band of control output $2 = 20 \times 0.5 = 10$ (%)

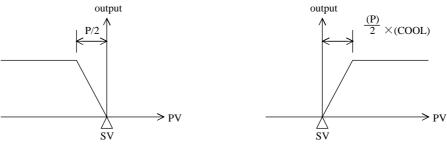
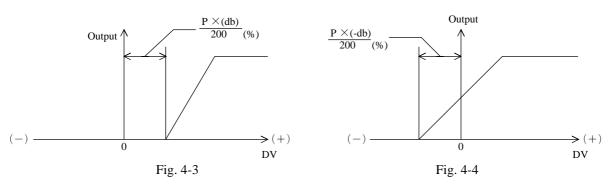


Fig. 4-1 Fig. 4-2

The control output 2 value corresponding to deviation can be changed. This can be changed according to setting of parameter dB.

(When dB is plus)

(When dB is minus)



(2) The tuning of dual output type

In the dual output type controller, the PID auto-tuning is not effective.

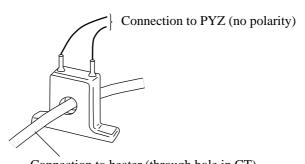
During PID auto-tuning, the cooling side output is OFF. After the auto-tuning, both the heating and cooling sides are operated with the same PID value.

Then set PID parameters, parameter cool and parameter dB with front panel keys.

During PID control, both the heating and cooling sides are the same in setting and operation. PID operation cannot be set individually. When the heating side is set in 2-position operation, the cooling side is also set in 2-position operation.

5. USE OF HEATER BREAK ALARM (OPTION)

- The current detector (CT) comes in 2 types, 0-30A type (CTL-6-SF) and 20-50A type (CTL-12-S36-8F). It should be set to the heater current being used.
- For setting alarm point, the parameter Hb is used.
- O Setting of alarm set point
 - ① With the controller output set to ON, apply a current to the heater.
 - ② While changing the alarm set point, locate the value at which the alarm operates (when changing the set point, be sure to wait for 3 seconds or more).
 - 3 When the operating point has been set, the final set point should be 70 to 80% of the operating point.
- By using a power common to the heater and this controller, the variation of the alarm operating point due to power fluctuation can be minimized.
 Set the parameter Tc for 6 sec. or more.
- To use heater alarm functions properly, set the second parameter P-CT to heater power voltage value.
- When heater is controlled with an actuator controlling phase angle, the heater break alarm can not be used.
- Connection of heater burnout detecting CT



Connection to heater (through hole in CT)

Fig. 5-1

O Connection example of heater break alarm (Type PYZ5, 9)

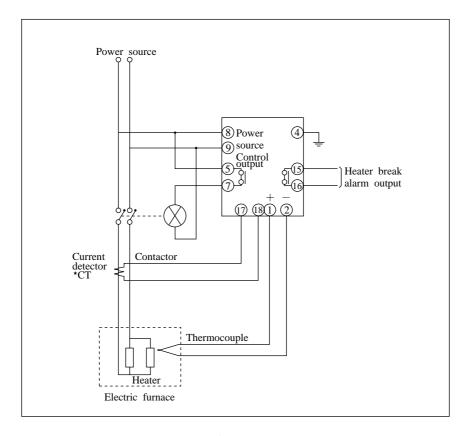


Fig. 5-2

Read the following when changing the functions of this controller.

6. CHANGE OF FUNCTIONS

The function specifications of this controller can be changed by changing the second block parameters. To change the functions, the second parameter should be called out.

6.1 Kinds of second parameter and meanings

Table 6-1 shows a list of second parameters and their meanings.

To call out of second parameter, operate the keys in the following order.

After the parameter " \mathcal{P} " has been selected, press the SEL key for about 5 seconds. In this way, the indicator shows " $\mathcal{P} = \sigma$!" and the controller is set in the second parameter mode. To return to the first block parameter mode, display " $\mathcal{P} = \sigma$!" and then press the SEL key for about 5 seconds.

When the key is not operated for 30 sec. or more, the parameter indication is reset to SV indication mode of the first block parameter. (Note that it is reset to PV indication mode is case of PYZ4.)

List of second block parameters

Table 6-1

Parameter symbol	Item	Meaning	Description	Initial value prior to delivery
P-n:	P-n1	Control operation	Setting of direct/reverse operation, and setting of burnout direction	Ordering specification
P - 53	P-n2	Input type	Setting of input signal type	Ordering specification
5-55	P-dF	Input filter time constant	Half of code value is time constant (sec.) (code: 0 to 201)	Code 20 (time constant; 10 sec)
P - 5t	P-SL	Lower limit of input range	Setting of lower limit value of input range	Ordering specification
P - 5U	P-SU	Upper limit of input range	Setting of upper limit value of input range	Ordering specification
P-85	P-Ab	Alarm type	Setting of alarm operation type	Ordering specification Unless otherwise specified, the function code 79(high/low limit deviation alarm) is set.
P - 8n	P-An	Hysterisis of alarm	Setting of hysteresis width then alarm output ON-OFF Setting range: $0-255^{\circ}\text{C}/^{\circ}\text{F}$	1
P-3P	Selection of the position of decimal point on the PV and SV indicator P-dP Decimal point position Code 0: without decimal point Code 2 Code 4		Code 0 : without decimal point Code 2	Ordering specification
P - 48	P-48		Parameter peculiar to the model. <i>Do not change</i> .	Specified by manufacturer
P-57	P-CT	Setting of heater rated voltage	When using heater burnout alarm, be sure to set the rated power voltage for the controller (setting range:85-265V)	100
PUBE	PVOF	PV offset	PV indicated value is shiftted, however PV is unchanged. (Setting range: -1999 to +2000)	0
SUDF	SVOF	SV offset	SV indicated value is shiftted, however SV is unchanged. (Setting range: -1999 to +2000)	0
P- F	P-F	°C/°F selection of measured value input	Only the measured values are changed over, so other parameters need to be changed. $^{\circ}$ C display: 0 $^{\circ}$ F display: 1	$PV (^{\circ}F) = \frac{9}{5} PV (^{\circ}C) + 32$
PLEE	PLC2		Setting need not be changed	Specified by manufacturer
PHER	PHC2		Same as above	Specified by manufacturer
358 t			Used to set desired parameters P, I, D, AL, AH, TC, HYS for display.	
d588	dSP2	P	Same as above for Hb, AT, TC2, COOL, db, PLC1, PHC1, PCUT.	
d583	dSP3		Same as above for BAL, AR	

6.2 Function setting

(1) Method of changing input type specifications

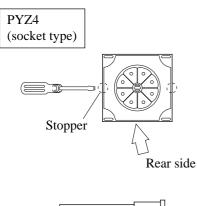
Input can be changed shown below.

- (b) Change from the thermocouple to resistance bulb
 - · Turn off the power of the controller, and pull out the controller from the case or the socket.
 - · Change the input select socket to RTD (resistance bulb) side.
 - · Set the controller into the case or on the socket, and turn on the power.
- (c) Change from resistance bulb to thermocouple select the parameter $\vec{r} \vec{r}_1 \vec{r}_2$
 - · Turn off the power of the controller, and pull out the controller from the case or the socket.
 - · Change the input select socket to TC (thermocouple) side.
 - · Set the controller into the case or on the socket, and turn on the power.
 - Change to the second block parameter, and select the parameter F mE. Set the code of desired thermocouple.
- (d) Change from DC 1 to 5V DC input to DC 4 to 20mA DC input Connect a resistor ($250\,\Omega$) to input terminal. The resistor should be purchased by user.
- (e) Change from 4 to 20mA DC to 1 to 5V DC Remove the resistor (250Ω) connected at input terminals.
- (f) Change from thermocouple or resistance bulb to 1 to 5V DC or 4 to 20mA DC. In this case, changing is not usable.

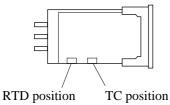
For input type code, refer to table 6-2. For changeover of internal switch, refer to Fig. 6-1 through 6-4.

Input type and code

Type	Code
Resistance bulb	
• Pt 100 (IEC)	0
Thermocouple	
• J	2
• K	3
• R	4
• S	6
• T	7
• N	12
• PL–II	13
Voltage/current	
• 1~5V DC	31
• 4~20mA DC	31



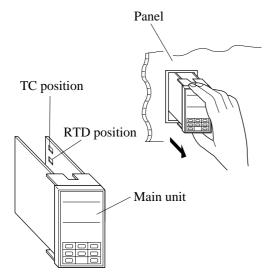
Attach a flat blade screwdriver to the hooks on the rear at the left and right sides to open the case, then push the inside of the main unit with finger tip.



Set the small socket to RTD position or TC position.

Fig. 6-1

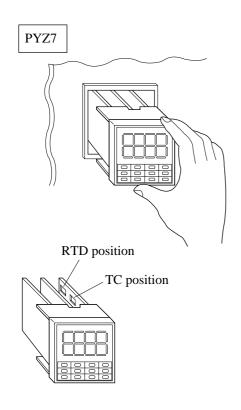
PYZ5



Push down until the lock is released.

Set the small socket to RTD position or TC position.

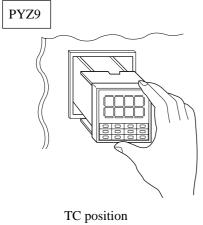
Fig. 6-2



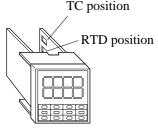
Push down until the lock is released.

Set the small socket to RTD position or TC position.

Fig. 6-3



Push down until the lock is release.



Set the small socket to RTD position or TC position.

Fig. 6-4

(2) Change of control action

Select the second parameter "P - r, r" and set the function code as shown in Table 6-3 and 6-4. Definition of reverse action and direct action

O Reverse action

This is used to control temperature by heating. When the temperature is higher than the set value, the controller output decreases.

O Direct action

This is used to control temperature by cooling. When the temperature is higher than the set value, the controller output increases.

For wire-break of thermocouple input and RTD input, the input value becomes the value specified by burnout direction.

As a result, when wire-break direction is set to upper limit and control output is set to reverse action, for example, the control output goes to lower limit in wire-break of input.

Table 6-3

	Standard type								
Function code	Burnout direction	Control output 1	Function code	Burnout direction	Control output 1				
0	Upper limit	Reverse action	1	Lower limit	Reverse action				
16	Upper limit	Direct action	17	Lower limit	Direct action				

Note) Function codes "0" and "17": Standard

Table 6-4

Dual output type								
Function	Burnout	Control	Control	Function	Burnout	Control	Control	
code	direction	output 1	output 2	code	direction	output 1	output 2	
2	Upper	Reverse	Direct	3	Lower	Reverse	Direct	
	limit	action	action		limit	action	action	
18	Upper	Direct	Direct	19	Lower	Direct	Direct	
10	limit	action	action		limit	action	action	
34	Upper	Reverse	Reverse	35	Lower	Reverse	Reverse	
34	limit	action	action	33	limit	action	action	
50	Upper	Reverse	Reverse	<i>5</i> 1	Lower	Direct	Reverse	
50	limit	action	action	51	limit	action	action	

Note) Function codes "2" and "3": Standard

(3) Change of alarm operation (option)

Alarm operation has 18 types of functions.

Select the second parameter " β - $\beta \beta$ " and set the function code as shown in Table 6-5. Then the alarm type can be changed.

The low alarm hold function inhibits the low alarm output at the beginning when the power of the controller is turned on.

By setting the upper/lower alarm in case of PYZ4, the alarm output is obtained by OR of upper and lower alarms.

In this case, their alarms can be displayed independently on the front panel.

On the high/high limit deviation alarm, the low-limit set value should be set in negative value using the high/low-limit function.

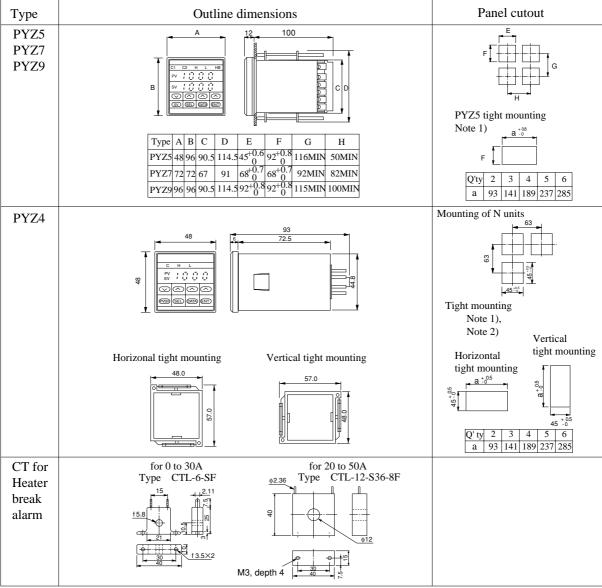
Table 6-5

	Functio	n		Action		Function code	Description
	High/low ala		AL	SV AF	-	15	Upper limit (H) and lower limit (L) for set value (SV).
larm	High alarm			SV AI	+	10	Alarm output is ON in the hatched area
Deviation alarm	Low alarm Without low	alarm hold	AL	SV		5	
De	High/low ala With low ala		AL	SV AH	1	79 (standard)	
	Low alarm With low ala	arm hold	AL	SV		69	
	High/high al			ALAH		19	Upper limit (H) and lower limit (L) within the range (0 to 100%).
e alarm	High/low ala Without low		AL	Al	-	3	Alarm output is ON in the hatched area
Absolute value alarm	High alarm			Al	4	2	
Absol	Low alarm Without low limit hold		AL			1	
	High/low alarm With low alarm hold		AL	Al	-	67	
	Low alarm With low alarm hold		AL			65	
	Low/low alarm ** Without low alarm hold		Al	HAL S		35	
alarm	Absolute value High	Deviation High **	SV	ALAH		23	Alarm output is ON in the hatched area
	High alarm	Low alarm	AL	SV AI	H	7	
ue+Devi	Low alarm	High alarm	AL	SV AI	=	11	
Absolute value+Deviation	Low alarm With low alarm hold	High alarm	AL	SV AI	H	75	
Abs	High alarm	Low alarm With low alarm hold	AL	SV AI	H	71	
	Low alarm	High alarm				179	Alarm output is ON within
	Absolute value	Absolute value	AL	Al	Н	117	the range between low alarm set value and high
Zone alarm	Deviation	Absolute value	AL	SV AI	 H	183	alarm set value. Alarm is output to Alarm 2
Zone	Absolute value	Deviation	AL	SV AI		187	terminal (PYZ5, PYZ7, PYZ9)
	Deviation	Deviation	AL	SV AI	 H	191	

^{*} in case of PYZ5, 7 and 9.

7. OUTLINE DIMENSIONS AND PANEL CUTOUT

(Unit: mm)



- Note 1) When the power source voltage is more than 200V, it is recommended to use a ventilating fan. 100V AC power should be used for vertical tight mounting (use of a ventilation fan is recommended).
- Note 2) When using 11-pin TP311SB socket, horizontal tight mounting is not available.
- Note 3) Vertical tight mounting is available only for ATXINS, 11GB socket.

8. TERMINAL CONNECTION DIAGRAM

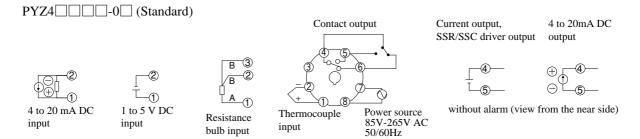


Fig. 8-1 (view from the rear side)

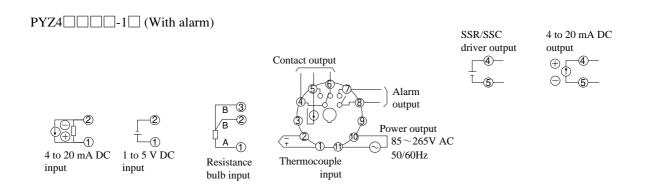
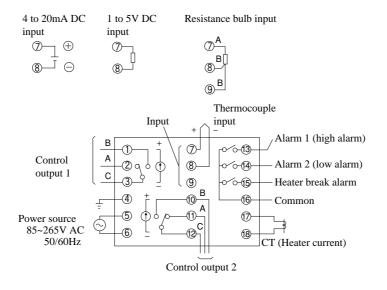


Fig. 8-2 (view from the rear side)

PYZ5, 9 Thermocouple input Current/SSR/SSC/output (10) 4 to 20mA DC 1 to 5V DC Resistance 2 11) Control output 2 bulb input input input 3 12 <u>A</u> B 4 **∕**○ **(**3) Alarm 1 (high alarm) (a) Alarm 2 (high alarm) <u>B</u> 250Ω Control 6 ° (15) Heater break alarm output 1 7 Common 8 17 Power source 85-265V AC -(9) 18 50/60Hz CT (Heater current) Control output 1 Control output 2 SSR/SSC driver 4 to 20 mA DC SSR/SSC driver 4 to 20 mA DC output output output output

Fig. 8-3



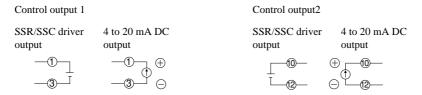


Fig. 8-4

9. CONTROL/ALARM OUTPUT AND INDICATING LAMP

Output and indication during operation

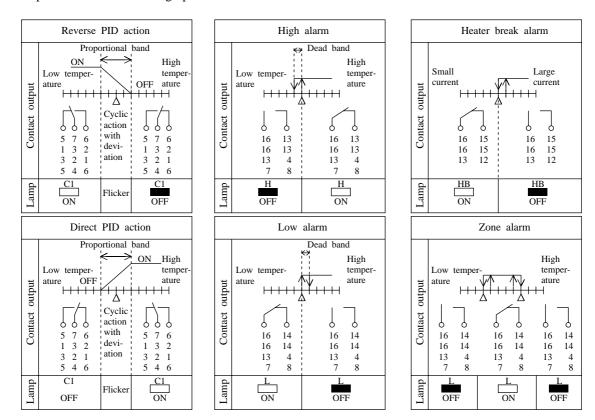


Fig. 9-1

Output and indication during operation

(Note) Terminal No. varies with type of instrument.

Terminal No.: Uppermost PYZ5, 9

Upper PYZ7

Lowermost...... PYZ4 DDD - 0

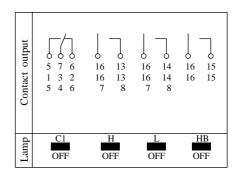
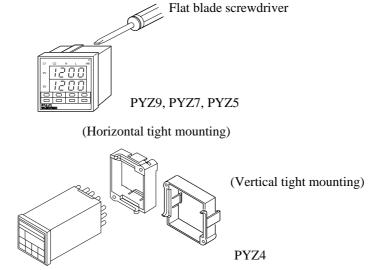


Fig. 9-2

10. CAUTIONS FOR INSTALLATION AND WIRING

○ Installation

- For front panel size of the instrument and the panel mounting size conform to DIN43700 Standards.
- Recommended panel of PYZ9, PYZ7 and PYZ5 is 1 to 8mm thick and the recommended panel of PYZ4 is 1 to 3.2mm thick.
- For installation of PYZ9, PYZ7 and PYZ5, attach the mounting brackets (two) on the top and bottom and tighten with a flat blade screwdriver to the torque of about 1.5 kg•cm. (Plastic case is used. Do not tighten excessively.)



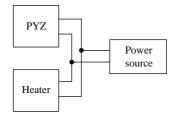
• For installation of PYZ4, insert the supplied panel frame from the rear side and secure it firmly until the main unit is fitted to the panel. When it cannot be fitted firmly, tighten the two screws lightly. (If the screws are tightened excessively, the frame may slip off the stopper.)

O Environment of installation location

- Do not install in a place with corrosive gases (sulfuric gas, ammonia, etc.)
- Do not install in a place subject to vibration, impact, water or high temperature.
- Do not install in a place where ambient temperature changes suddenly or radiation from furnace is present. Ambient temperature of installation location should be -10 to +50 $^{\circ}$ C.

Wiring

- This controller is not equipped with a power switch and fuse. These should be mounted if necessary (fuse rating: 250V, 1A).
- For thermocouple input, connect the specified compensating lead wire.
- For resistance bulb input, use a lead wire having a small resistance.
- Input signal and power cables connected to the instrument should be wired away from power line and load line to minimize inductive noise.
- For instrument with heater break alarm, use the same power source for the heater and the controller to minimize the variation of alarm operating point due to power voltage.



• Input signal cable should be separated from the output signal cable. Be sure to use shielded cables.

- O Use of controller output for sequence circuit
 - When power is ON, it takes about 4 to 5 seconds until the internal relay starts operating. This should be taken into account when using the controller contact output for the sequence circuit.

• Wiring of load circuit

- A load connected to the control output should be used within the rating. If it exceeds the rating, it should be connected through a contactor having a larger rating.
 - The contact output type has its own operating life so the control cycle (TC and TC2) should be extended so as not to affect the control function. In the case of the 2-position control, the hysteresis width should be increased making sure that it does not affect the control function. Also, care should be taken with regard to the alarm output and heater break alarm output when using.
- When the controller is used for frequent operation such as for proportional action, use SSR or SSC output type auxiliary relay, because if a load corresponding to the full capacity of output relay is connected, the life of it is shortened.

Electromagnetic relay:

Proportional cycle is more than 30 sec.

SSC, SSR:

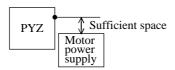
Proportional cycle is more than 1 sec.

Contact output life:

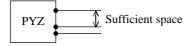
Mechanical More than 10⁷ cycles (at no load)

Electrical More than 10⁵ cycles (at 220V AC/3A, resistive load)

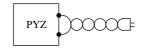
- O Current output ripple
 - Current output (4 to 20mA DC) contains about 0.2mA/2 Hz of ripples.
- O Removal of noise
 - The instrument should be installed as far as away possible from a device generating high frequency noise.



• Input signal and power cables connected to the instrument should be wired away from power line and load line to minimize inductive noise.



• Instrument power cable should preferably be twisted to avoid noise.



- When much noise is generated from external wiring, use the following preventive measure.
- When a contactor is connected as a load for digital output such as a relay contact or alarm output, use a surge absorber on the coil of the contactor.

Surge absorber Fuji Z-trap (ENB461D-14A, 220V AC)

• When much noise is generated from power supply, use an insulating transformer and a noise filter.

(Example: TDK ZMB22R5-11 Noise Filter)

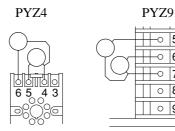
• To protect relay output from ON/OFF surge and to ensure a long service life, we recommend you to use Fuji Z-trap.

Type: ENC241D-05A (100V AC) ENC471D-05A (200V AC)

Mounting position: Connected between relay control output terminals

Example)

ATX2PSB



O Wiring for 4 to 20mA DC input

• When ordering instrument of 4 to 20mA DC input specifications, a resistor (250 Ω) will be supplied as an accessory for connection to the input terminal.

0 8

- When using the final control element in the non-insulated type, use the temperature sensor in non-grounding type.
- O Wiring for 1 to 5V DC input
 - Use of the resistor (250 Ω) supplied for 4 to 20 mA DC input is not required.
- OSSR/SSC drive output and 4 to 20 mA DC output are not isolated electrically from the internal circuit. Use a non-grounded type resistance bulb or thermocouple as a sensor.
- O Connection of PYZ9, PYZ7 and PYZ5

For connection, use round type or fork type M3.5 clamping terminal. The maximum outside diameter of the terminal should be less than 8mm.

- O Caution prior to use
 - To clean the front panel of the instrument, do not use benzine, thinner, etc., as it damages the panel. It should be washed with water or soapy water until the dirt and dust are removed. (The front panel of the instrument is water/dust-proof type based on IEC IP65 standards.)
 - Do not use any tool having a sharp tip when operating the keys on the front panel.

11. SPECIFICATIONS

Table 11-1

Input signal	Thermocouple/resistance bulb, 1 to 5V DC, 4 to 20mA DC		
Control output signal	Contact (220V AC, 3A, 1c contact), 4 to 20mA DC (load resistance: less than 600Ω) SSR/SSC drive (24V DC typ./60mA at ON, 0.3V DC max. at OFF)		
Control action	PID action (2-position action, proportional action possible)		
Indicator accuracy	$\pm 0.5\%$ FS ± 1 digit ($\pm 5\%$ FS ± 1 digit : R, S thermocouple 0 to 400%)		
Operating cycle	0.5 sec.		
Indication system	7-segment LED, 4 digits		
Effect of external resistance	About 0.5μ V/ Ω (Thermocouple input) Reading $0.015\%/\Omega$ (per wire), resistance bulb		
Attachment	High/low alarm (PYZ4: high or low alarm) Alarm output: 220V AC, 1A, 1a contact, 2 points (PYZ4: 1 point) Heater break alarm (Contacted to separately installed Fuji's CT) Alarm output: 220V AC, 1A, 1a contact		
Power supply	85 to 265V AC, 50/60Hz		
Power consumption	About 10VA/100V AC, about 18VA/220V AC		
Enclosure case	Plastic housing		
Ambient temperature	-10 to +50℃		
Ambient humidity	90% RH or less		

Table 11-1 Input specification

Figure in () include those with decimal point.

Input	Range ($^{\circ}$ C)	Range (°F)	Remarks	
Pt 100 (IEC)	$0\sim50, \cdots400$ $(0.0\sim100.0, \cdots300.0)$ $-150, \cdots-100\sim50, \cdots200$ $(-150.0, \cdots-100.0\sim50.0, \cdots200.0)$	32~122, ···752 -238, ···-148~122, ···392	guaranteed when	
J	0~200, ···1000 (0.0~200.0, ···300.0)	32~392,···1832	the range setting is below the minimum.	
K	$0\sim200, \cdots 1200$ (0.0 $\sim200.0, \cdots 300.0$)	32~392,····2192	Accuracy is not guaranteed when the reading is out of range. $F = \frac{9}{5} ^{\circ}\text{C} + 32$ (NBC standards)	
R	0~1000, ···1600	32~1832, ···2912		
Т	$0\sim200, \cdots400$ $(0.0\sim200.0, \cdots300.0)$ $-200, \cdots-100\sim200, \cdots400$ $(-199.9, \cdots-100.0\sim200.0, \cdots300.0)$	32~392, ···752 -328, ···-148~392, ···752		
N and PL—II	0~200, ···1300 (0.0~200.0, ···300.0)	32~392, ···2372	(1 (D C sumumus)	
1~5V DC 4~20mA DC	−1999∼3000 (Industrial value setting)		Setting of decimal point is possible.	

Note) When the span of input range is large, the indication may be limited to $3276^{\circ}F$ or $327.6^{\circ}C$ in the over-range zone. Avoid a wide range setting unnecessarily.

12. ORDERING CODE

Table 12-1

1 2 3 4 5 6 7 8 9 10 digit							
PYZ	2] - [Ī	Description	
		' -		-	1	Front panel size	
4	ļļ					48×48mm	
5	ļļ					48×96mm	
7	ļļ			-		72×72mm	
9	ļļ			-		96×96mm	
]	Input signal	
T	ļļ			ļ.,		Thermocouple [°C]	
R	ļļ			-		Thermocouple [°F]	
N	ļļ					Resistance bulb, Pt100 Ω, 3-wire (IEC) [°C] (*1)	
S	ļļ			Resistance bulb, Pt100 Ω, 3-wire (IEC) [°F] (*1)			
B	ļļ			4 to 20 mA DC (*2)			
A	ļļ			ļ.,		1 to 5V DC	
				Ť		Control output 1	
A	ļļ			+-		Contact reverse action PID control	
В	ļļ					Contact direct action PID control	
C						SSR or SSC drive reverse action PID control	
D						SSR or SSC drive direct action PID control	
E						4-20 mA DC reverse action PID control	
F						4-20 mA DC direct action PID control	
					-	Control output 2 (Not for PYZ 4)	
	Υ					Without output 2	
A						Contact reverse action PID control	
	В			-}		Contact direct action PID control	
c						SSR or SSC drive reverse action PID control Dual output	
D						SSR or SSC drive direct action PID control	
	E					4 to 20 mA DC reverse action PID control	
F						4 to 20 mA DC direct action PID control	
				1	1	Additional functions	
		C)			None	
		1				With high/low alarm	
		2	2	+-		With heater break alarm (Note 2)	
3			3			With high/low alarm and heater break alarm (Note 2)	
		_			A	Attaching socket	
			Υ	,		None(specifily when PYZ5, 7, 9 is used)	
		ſ	A	·		With ATX2PSB (rear panel screw terminal)	
0 -:	4 -1-]	В	;		With ATXINS (US socket)	
8-pin terminal (without alarm) (for 9th digit code) 11-pin terminal (without alarm) (for 9th digit code)			С	;		With TP28S (rear panel screw terminal)	
			D) 		With TP28X (rail mounting)	
			_ E	;		With TP311SB (rear panel screw terminal)	
			F			With 11GB (rear panel socket)	
			G	i		With TP311SS (rear panel screw terminal)	
						With TK7A5807P9 (front panel, rail mounting)	

Note 1) Symbol for resistance bulb is as follows

- Note 2) The supplied resistor (250 Ω) should be connected to the terminal. (This resistor is not required for 1 to 5V DC input.)
- Note 3) Heater break alarm is not available for PYZ4 and 4 to 20mA DC output.
- Note 4) Specify control output 2 for dual output type.

Mounting socket ordering (PYZ4)

Туре	Mounting	Application
ATX2PSB	Panel flush mounting	
ATX1NS (US SOCKET)	Panel flush mounting	For non alarm trina
TP28S	Wall mounting	For non alarm type
TP28X	Rail mounting	
TP311SB	Panel flush mounting	
11GB	Panel flush mounting	For alarm type
TP311S	Wall mounting	1 or ararm type
TK7A5807P9	Rail mounting	